#### *General Description*

The MAX4356 is a 16  $\times$  16 highly integrated video crosspoint switch matrix with input and output buffers and On-Screen Display (OSD) Insertion. This device operates from dual  $\pm 3V$  to  $\pm 5V$  supplies or from a single +5V supply. Digital logic is supplied from an independent single  $+2.7V$  to  $+5.5V$  supply. Individual outputs can be switched between an input video signal source and OSD information through an internal, dedicated fast 2:1 mux (40ns switching times) located before the output buffer. All inputs and outputs are buffered, with all outputs able to drive standard  $75\Omega$ reverse-terminated video loads.

The switch matrix configuration and output buffer gain are programmed via an SPI/QSPI™-compatible, threewire serial interface and initialized with a single update signal. The unique serial interface operates in two modes facilitating both fast updates and initialization. On power-up, all outputs are initialized in the disabled state to avoid output conflicts in large-array configurations.

Superior flexibility, high integration, and space-saving packaging make this nonblocking switch matrix ideal for routing video signals in security and video-ondemand systems.

The MAX4356 is available in a 128-pin TQFP package and specified over an extended -40°C to 85°C temperature range.

*Applications*

Security Systems Video Routing Video-on-Demand Systems





*SPI and QSPI are trademarks of Motorola, Inc.*

#### **MAXM**

#### *Features*

♦ **16** ✕ **16 Nonblocking Matrix with Buffered Inputs and Outputs**

**MAXM** 

- ♦ **Operates from ±3V, ±5V, or +5V Supplies**
- ♦ **Individually Programmable Output Buffer Gain (AV = +1V/V or +2V/V)**
- ♦ **High-Impedance Output Disable for Wired-OR Connections**
- ♦ **Fast-Switching (40ns) 2:1 OSD Insertion Mux**
- ♦ **0.1dB Gain Flatness to 14MHz**
- ♦ **-62dB Crosstalk, -110dB Isolation at 6MHz**
- ♦ **0.02%/0.12° Differential Gain/Differential Phase Error**
- ♦ **Low 195mW Power Consumption (0.76mW per Point)**

### *Ordering Information*



**Pin Configuration appears at end of data sheet.**

## *Functional Diagram*



**\_ Maxim Integrated Products 1**

**For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.**

# **MAX4356** *MAX4356*

#### **ABSOLUTE MAXIMUM RATINGS**





*Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.*

## **DC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES ±5V**

(V<sub>CC</sub> = +5V, V<sub>EE</sub> = -5V, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = 0, V<sub>OSDFILL</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)



## **DC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES ±5V (continued)**

(V<sub>CC</sub> = +5V, V<sub>EE</sub> = -5V, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub>\_= 0, V<sub>OSDFILL</sub> = 0, R<sub>L</sub> = 150Ω to AGND, and T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T $_A$  = +25°C.)



## **DC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES ±3V**

(V<sub>CC</sub> = +3V, V<sub>EE</sub> = -3V, V<sub>DD</sub> = +3V, AGND = DGND = 0, V<sub>IN</sub> = 0, V<sub>OSDFILL</sub> = 0, R<sub>L</sub> = 150Ω to AGND, and T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T $_A$  = +25°C.)



**MAXM** 

## **DC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES ±3V (continued)**

(V<sub>CC</sub> = +3V, V<sub>EE</sub> = -3V, V<sub>DD</sub> = +3V, AGND = DGND = 0, V<sub>IN</sub> = 0, V<sub>OSDFILL</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)



## **DC ELECTRICAL CHARACTERISTICS—SINGLE SUPPLY +5V**

 $(V_{CC} = +5V, V_{EE} = 0, V_{DD} = +5V, AGND = DGND = 0, V_{IN} = V_{OSDFILL} = +1.75V, AV = +1V/V, R<sub>L</sub> = 150\Omega$  to AGND, and TA = TMIN to T<sub>MAX</sub>, unless otherwise noted. Typical values are at  $TA = +25^{\circ}C$ .)



## **DC ELECTRICAL CHARACTERISTICS—SINGLE SUPPLY +5V (continued)**

 $(V_{CC} = +5V, V_{EE} = 0, V_{DD} = +5V, AGND = DGND = 0, V_{IN} = V_{OSDFILL} = +1.75V, Av = +1V/V, R_L = 150\Omega$  to AGND, and T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.)



**MAXM** 

## **LOGIC-LEVEL CHARACTERISTICS**

 $(V_{CC} - V_{EE})$  = +4.5V to +10.5V,  $V_{DD}$  = +2.7V to +5.5V, AGND = DGND = 0, V<sub>IN</sub> = V<sub>OSDFILL</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and  $T_A$  = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.) (Note 2)



## **AC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES ±5V**

(V<sub>CC</sub> = +5V, V<sub>EE</sub> = -5V, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = V<sub>OSDFILL</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = +25°C, unless otherwise noted.)



# **MAX4356** *MAX4356*

### **AC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES ±5V (continued)**

 $(V_{CC} = +5V, V_{EE} = -5V, V_{DD} = +5V, AGND = DGND = 0, V_{IN\_} = V_{OSDFILL} = 0, R<sub>L</sub> = 150Ω to AGND, AV = +1V/V, and T<sub>A</sub> = +25°C,$ unless otherwise noted.)



## **AC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES ±3V**

 $(V_{CC} = +3V, V_{EE} = -3V, V_{DD} = +3V, AGND = DGND = 0, V_{IN} = V_{OSDFILL} = 0, R_L = 150Ω to AGND, AV = +1V/V, and T<sub>A</sub> = +25°C,$ unless otherwise noted.)



**MAXM** 

## **AC ELECTRICAL CHARACTERISTICS—DUAL SUPPLIES ±3V (continued)**

 $(V_{CC} = +3V, V_{EE} = -3V, V_{DD} = +3V, AGND = DGND = 0, V_{IN} = V_{OSDFILL} = 0, R_L = 150\Omega$  to AGND,  $Av = +1V/V$ , and  $T_A = +25°C$ , unless otherwise noted.)



### **AC ELECTRICAL CHARACTERISTICS—SINGLE SUPPLY +5V**

(V<sub>CC</sub> = +5V, V<sub>EE</sub> = 0, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = V<sub>OSDFILL</sub> = 1.75V, R<sub>L</sub> = 150 $\Omega$  to AGND, A<sub>V</sub> = +1V/V, and T<sub>A</sub> = +25°C, unless otherwise noted.)



**MAXM** 

## **SWITCHING CHARACTERISTICS**

 $((Vec - V_{EE}) = +4.5V$  to +10.5V,  $V_{DD} = +2.7V$  to +5.5V, DGND = AGND = 0,  $V_{IN-} = V_{OSDFILL-} = 0$  for dual supplies,  $V_{IN-} =$ VOSDFILL\_ = +1.75V for single supply, RL = 150 $\Omega$  to AGND, CL = 100pF, Ay = +1V/V, and TA = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)



Note 1: Associated output voltage may be determined by multiplying the input voltage by the specified gain (A<sub>V</sub>) and adding output offset voltage. Gain is specified for IN\_ and OSDFILL\_ signal paths.

**Note 2:** Logic-level characteristics apply to the following pins: DIN, DOUT, SCLK, CE, UPDATE, RESET, A3–A0, MODE, AOUT, and OSDKEY\_.

**Note 3:** Switching transient settling time is quaranteed by the settling time (ts) specification. Switching transient is a result of updating the switch matrix.

**Note 4:** Input test signal: 3.58MHz sine wave of amplitude 40IRE superimposed on a linear ramp (0 to 100IRE). IRE is a unit of video-signal amplitude developed by the International Radio Engineers: 140IRE = 1.0V.

**Note 5:** All devices are 100% production tested at T<sub>A</sub> = +25°C. Specifications over temperature limits are guaranteed by design.



### **Symbol Definitions** *Naming Conventions*

- All parameters with time units are given a "t" designation, with appropriate subscript modifiers.
- Propagation delays for clocked signals are from the active edge of clock.
- Propagation delay for level-sensitive signals is from input to output at the 50% point of a transition.
- Setup and hold times are measured from the 50% point of signal transition to the 50% point of the clocking signal transition.
- Setup time refers to any signal that must be stable before the active clock edge, even if the signal is not latched or clocked itself.
- Hold time refers to any signal that must be stable during and after active clock edge, even if the signal is not latched or clocked.
- Propagation delays to unobservable internal signals are modified to setup and hold designations applied to observable I/O signals.



**MAX4356** *MAX4356*

*Figure 1. Timing Diagram*

*Typical Operating Characteristics—Dual Supplies ±5V*

/VI /IXI /VI



# **MAX4356** *MAX4356*

### *Typical Operating Characteristics—Dual Supplies ±5V (continued)*

(V<sub>CC</sub> = +5V and V<sub>EE</sub> = -5V, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = +25°C, unless otherwise noted.)



*Typical Operating Characteristics—Dual Supplies ±5V (continued)*  $(V_{CC} = +5V$  and  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ , AGND = DGND = 0,  $V_{IN} = 0$ , R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = +25°C, unless otherwise noted.)



/VI /IXI /VI

**MAX4356** *MAX4356*

#### *Typical Operating Characteristics—Dual Supplies ±5V (continued)*

(V<sub>CC</sub> = +5V and V<sub>EE</sub> = -5V, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = +25°C, unless otherwise noted.)







**DIFFERENTIAL GAIN AND PHASE (RL = 150**Ω**)**



**DIFFERENTIAL GAIN AND PHASE (RL = 1k**Ω**)** DIFF PHASE (°) DIFF GAIN (%) 0.004 0.002 0.000  $\Sigma - 0.002$ -0.004 0 10 20 30 40 50 60 70 80 90 100 0.03  $\circ$ PHASE 0.02 0.01 0.00 **JEF** -0.01





**MEDIUM-SIGNAL PULSE RESPONSE WITH** CAPACITIVE LOAD ( $C_L = 30pF$ ,  $Ay = +1V/V$ )



**LARGE-SIGNAL PULSE RESPONSE WITH** CAPACITIVE LOAD ( $C_L = 30pF$ ,  $A_V = +2V/V$ )

MAX4356 toc34





**LARGE-SIGNAL PULSE RESPONSE WITH CAPACITIVE LOAD (CL = 30pF, AV = +1V/V)** MAX4356 toc33



**MEDIUM-SIGNAL PULSE RESPONSE WITH CAPACITIVE LOAD (CL = 30pF, AV = +2V/V)** MAX4356 toc36



*Typical Operating Characteristics—Dual Supplies ±5V (continued)*

 $(V_{CC} = +5V$  and  $V_{EE} = -5V$ ,  $V_{DD} = +5V$ , AGND = DGND = 0,  $V_{IN} = 0$ , R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = +25°C, unless otherwise noted.)





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**OSD SWITCHING TRANSIENT (100IRE LEVEL SWITCH) (A<sub>V</sub> = +2V/V)** 



50ns/div



**RESET DELAY vs. CRESET**

**SUPPLY CURRENT vs. TEMPERATURE**



*IVI AXI IVI* 

#### *Typical Operating Characteristics—Dual Supplies ±3V*

(V<sub>CC</sub> = +3V and V<sub>EE</sub> = -3V, V<sub>DD</sub> = +3V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = +25°C, unless otherwise noted.)



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**MAX4356** *MAX4356*

## *Typical Operating Characteristics—Dual Supplies ±3V (continued)*

(V<sub>CC</sub> = +3V and V<sub>EE</sub> = -3V, V<sub>DD</sub> = +3V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = +25°C, unless otherwise noted.)





noted.)



/VI*/*IXI*/*VI

*MAX4356*

**MAX4356** 





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*MAX4356*

**MAX4356** 

#### *Typical Operating Characteristics—Dual Supplies ±3V (continued)*

(V<sub>CC</sub> = +3V and V<sub>EE</sub> = -3V, V<sub>DD</sub> = +3V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, and T<sub>A</sub> = +25°C, unless otherwise noted.)









**(100IRE LEVEL SWITCH)**MAX4356 toc80  $Ay = +2V/V$ 

**OSD SWITCHING TRANSIENT** 

## **VOUTO** 500mV/div VOSDKEY0 3V/div 100IRE 0IRE

50ns/div

*Typical Operating Characteristics—Single Supply +5V* (V<sub>CC</sub> = +5V and V<sub>EE</sub> = 0, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, A<sub>V</sub> = +1V/V, and T<sub>A</sub> = +25°C, unless oth-

erwise noted.)



**MAXIM** 

**MAX4356** *MAX4356*

*Typical Operating Characteristics—Single Supply +5V (continued)*

**CROSSTALK vs. FREQUENCY**

(V<sub>CC</sub> = +5V and V<sub>EE</sub> = 0, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, A<sub>V</sub> = +1V/V, and T<sub>A</sub> = +25°C, unless otherwise noted.)













**INPUT VOLTAGE NOISE vs. FREQUENCY**





**POWER-SUPPLY REJECTION RATIO**



1



MAX4356 toc98

INPUT 1V/div





 $MAXI/M$ 

## *Typical Operating Characteristics—Single Supply +5V (continued)*

(V<sub>CC</sub> = +5V and V<sub>EE</sub> = 0, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, A<sub>V</sub> = +1V/V, and T<sub>A</sub> = +25°C, unless otherwise noted.)



*IVI AXI IVI* 

*Typical Operating Characteristics—Single Supply +5V (continued)*

RESET DELAY (s)

(V<sub>CC</sub> = +5V and V<sub>EE</sub> = 0, V<sub>DD</sub> = +5V, AGND = DGND = 0, V<sub>IN</sub> = 0, R<sub>L</sub> = 150 $\Omega$  to AGND, A<sub>V</sub> = +1V/V, and T<sub>A</sub> = +25°C, unless otherwise noted.)







**RESET DELAY vs. CRESET** 10  $\begin{array}{ccccc} & & & & & & \end{array}$ <br>
1p 10p 10p 100p 1n 10n 100n 1µ 10µ 10y 10y 1 100m 10m RESET DELAY (S) 1m 100µ 10µ  $1\mu$ 100n 10n CRESET (F)





/VI*/*IXI*/*VI

## *Pin Description*





#### *Functional Diagram*



## *Detailed Description*

The MAX4356 is a highly integrated  $16 \times 16$  nonblocking video crosspoint switch matrix. All inputs and outputs are buffered, with all outputs able to drive standard  $75\Omega$  reverse-terminated video loads.

A 3-wire interface programs the switch matrix and initializes with a single update signal. The unique serial interface operates in one of two modes: Complete Matrix Mode (Mode 1) or Individual Output Address Mode (Mode 0).

In the *Functional Diagram,* the signal path of the MAX4356 is from the inputs (IN0–IN15), through the switching matrix, buffered by the output amplifiers, and presented at the output terminals (OUT0–OUT15). The other functional blocks are the serial interface and control logic. Each of the functional blocks is described in detail below.

#### *Analog Outputs*

The MAX4356 outputs are high-speed voltage feedback amplifiers capable of driving 150Ω (75Ω back-terminated) loads. The gain,  $Ay = +1$ V/V or  $+2V/V$ , is selectable through programming bit 4 of the serial control word. Amplifier compensation is automatically opti-

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$$

mized to maximize the bandwidth for each gain selection. Each output can be individually enabled and disabled through bit 5 of the serial control word. When disabled, the output is high impedance, presenting typically a 4kΩ load, and 3pF output capacitance, allowing multiple outputs to be connected together in building large arrays. On power-up (or asynchronous RESET), all outputs are initialized in the disabled state to avoid output conflicts in large array configurations. The programming and operation of the MAX4356 is output referred. Outputs are configured individually to connect to any one of the 16 analog inputs, programmed to the desired gain (A $v = +1$ V/V or  $+2V/V$ ), or disabled in a high-impedance state.

#### *Analog Inputs*

The MAX4356 offers 16 analog input channels. Each input is buffered before the crosspoint switch matrix, allowing one input to cross-connect to up to 16 outputs. The input buffers are voltage feedback amplifiers with high input impedance and low-input bias current. This allows the use of very simple input clamp circuits.

## **Table 1. Operation Truth Table**

*MAX4356*

**MAX4356** 



#### *OSDFILL and OSDKEY Inputs*

Intended for on-screen display insertion, the 16 OSD-FILL inputs are buffered analog signal inputs that are routed exclusively to a dedicated output buffer through a fast 2:1 Mux. The signal presented to the output buffer is selected from the programmed analog input signal (IN\_) and the dedicated OSDFILL input signal. Each OSD Insertion Mux is controlled through the corresponding OSDKEY digital input to provide fast pixel switching.

*Switch Matrix* The MAX4356 has 256 individual T-switches making a 16 x 16 switch matrix . The switching matrix is 100% nonblocking, which means that any input may be routed to any output. The switch matrix programming is output-referred. Each output may be connected to any one of the 16 analog inputs. Any one input can be routed to all 16 outputs with no signal degradation.

#### *Digital Interface*

The digital interface consists of the following pins: DIN, DOUT, SCLK, AOUT, UPDATE, CE, A3–A0, MODE, and RESET. DIN is the serial data input; DOUT is the serial data output. SCLK is the serial data clock that clocks data into the Data Input registers (Figure 2). Data at DIN is loaded at each falling edge of SCLK. DOUT is the data shifted out of the 96-bit Complete Matrix Mode (Mode = 1). DIN passes directly to DOUT when in Individual Output Address Mode (Mode = 0).

The falling edge of UPDATE latches the data and programs the matrix. When using individual output address mode, the address recognition output AOUT drives low when control word bits D13 to D10 match the address programming inputs (A3–A0) and UPDATE is low. Table 1 is the operation truth table.

#### *Programming the Matrix*

The MAX4356 offers two programming modes: individual output address mode and complete matrix mode.



# **Table 3. Chip Address Programming for MAX4356** *MAX4356* **16-Bit Control Word (Mode 0: Individual Output Address Mode)**



output gain-set bit, and input address bits (Tables 2 through 6, and Figure 2).

In mode 0, data at DIN passes directly to DOUT through the data routing gate (Figure 3). In this configuration, the 16-bit control word is simultaneously sent to all chips in an array of up to 16 addresses.

#### **Complete Matrix Mode (MODE = 1)**

Drive MODE to logic high to select mode 1. A single 96-bit control word consisting of 16 six-bit control words programs all outputs. The 96-bit control word's first 6-bit control word (MSBs) programs output 15, and the last 6-bit control word (LSBs) programs output 0 (Table 7 and Figures 4 and 5). Data clocked into the 96-bit Complete Matrix Mode register is latched on the falling edge of UPDATE, and the outputs are immediately updated.

#### **Initialization String**

The Complete Matrix Mode (Mode  $= 1$ ) is convenient to use to program the matrix at power-up. In a large matrix consisting of many MAX4356 devices, all the devices can be programmed by sending a single-bit

# *16x16 Nonblocking Video Crosspoint Switch with On-Screen Display Insertion and I/O Buffers*

#### **Table 2. 16-Bit Serial Control Word Bit Assignments (Mode 0: Individual Output Address Mode)**



These two distinct programming modes are selected by toggling a single MODE pin high or low. Both modes operate with the same physical board layout. This flexibility allows initial programming of the IC by daisychaining and sending one long data word while still being able to address immediately and update individual outputs in the matrix.

**Individual Output Address Mode (MODE = 0)**

Drive MODE to logic low to select mode 0. Individual outputs are programmed through the serial interface with a single 16-bit control word. The control word consists of two don't care MSBs, the chip address bits, output address bits, an output enable/disable bit, an

#### **MAXIM**



*Figure 2. Mode 0: Individual Output Address Mode Timing and Programming Example*

#### **Table 4. Chip Address A3–A0 Pin Programming**



## **Table 5. Output Selection Programming**





*Figure 3. Serial Interface Block Diagram*

#### **Table 6. Input Selection Programming**



#### **Table 7. 6-Bit Serial Control Word Bit Assignments (Mode 1: Complete Matrix Mode)**



# **MAX4356** *MAX4356*



*Figure 4. 6-Bit Control Word and Programming Example (Mode 1: Complete Matrix Mode Programming)*



*Figure 5. Mode 1: Complete Matrix Mode Programming*

stream equal to n x 96 bits, where n is the number of MAX4356 devices on the bus. The first 96-bit data word programs the last MAX4356 in line (see *Matrix Programming under Applications Information).*

#### *On-Screen-Display Fast Mux*

The MAX4356 features an asynchronous dedicated 2:1 Mux for each output buffer amplifier. Fast 40ns switching times enable pixel switching for on-screen-display (OSD) information such as text or other picture-in-picture signals (Figure 1). OSDFILL\_ inputs are buffered analog inputs connected to each dedicated OSD Mux. Switching between the programmed IN\_ input from the crosspoint switch matrix and the OSDFILL\_ is accomplished by driving the dedicated OSDKEY\_ digital input. A logic low on OSDKEYi routes the analog signal at OSDFILL; to the OUT; output buffer. OSDKEY\_ control does not affect the crosspoint switch matrix programming or the output buffer enable/disable or gain-set programming.

**RESET** The MAX4356 features an asynchronous bidirectional RESET with an internal 20k $\Omega$  pullup resistor to V<sub>DD</sub>. When RESET is pulled low, either by internal circuitry, or driven externally, the analog output buffers are latched into a high-impedance state. After RESET is released, the output buffers remain disabled. The outputs may be enabled by sending a new 96-bit data word or a 16-bit individual output address word. A reset is initiated from any of three sources. RESET can be driven low by external circuitry to initiate a reset, or RESET can be pulled low by internal circuitry during power-up (power-on reset) or thermal shutdown.

Since driving RESET low only clears the output buffer enable bit in the matrix control latches, RESET can be used to disable all outputs simultaneously. If no new data has been loaded into the 96-bit complete matrix mode register, a single UPDATE restores the previous matrix control settings.

#### *Power-On-Reset*

The power-on reset ensures all output buffers are in a disabled state when power is initially applied. A  $V<sub>DD</sub>$ voltage comparator generates the power-on-reset. When the voltage at V<sub>DD</sub> is less than 2.5V, the poweron-reset comparator pulls RESET low through internal circuitry. As the digital supply voltage ramps up crossing 2.5V, the MAX4356 holds RESET low for 40ns (typ). Connecting a small capacitor from RESET to DGND extends the power-on-reset delay. See Power-on Reset vs. RESET Capacitance in the *Typical Operating Characteristics.*

#### *Thermal Shutdown*

The MAX4356 features thermal shutdown protection with temperature hysteresis. When the die temperature exceeds +150°C, the MAX4356 pulls RESET low, disabling the output buffers. When the die cools by 20°C, the RESET pulldown is deasserted, and output buffers remain disabled until the device is programmed again.

#### *Applications Information*

#### *Building Large Video Switching Systems*

The MAX4356 can be easily used to create larger switching matrices. The number of ICs required to implement the matrix is a function of the number of input channels, the number of outputs required, and whether the array needs to be nonblocking or not. The most straightforward technique for implementing nonblocking matrices is to arrange the building blocks in a grid. The inputs connect to each vertical bank of devices in parallel with the other banks. The outputs of each building block in a vertical column connect together in a wired-OR configuration. Figure 6 shows a 128-input, 32-output, nonblocking array using the MAX4356 16 x 16 crosspoint devices.

The wired-OR connection of the outputs shown in the diagram is possible because the outputs of the IC devices can be placed in a disabled or high-impedance output state. This disable state of the output buffers is designed for a maximum impedance vs. frequency while maintaining a low output capacitance. These characteristics minimize the adverse loading effects from the disabled outputs. Larger arrays are constructed by extending this connection technique to more devices.

#### *Driving a Capacitive Load*

Figure 6 shows an implementation requiring many outputs to be wired together. This creates a situation where each output buffer sees not only the normal load impedance, but also the disabled impedance of all the other outputs. This impedance has a resistive and a capacitive component. The resistive components reduce the total effective load for the driving output. Total capacitance is the sum of the capacitance of all the disabled outputs and is a function of the size of the matrix. Also, as the size of the matrix increases, the length of the PC board traces increases, adding more capacitance. The output buffers have been designed to drive more than 30pF of capacitance while still maintaining a good AC response. Depending on the size of the array, the capacitance seen by the output can exceed this amount. There are several ways to improve the situation. The first is to use more building-block





*Figure 6. 128 x 32 Nonblocking Matrix Using 16 x 16 Crosspoint Devices*

crosspoint devices to reduce the number of outputs that need to be wired together (see Figure 7).

In Figure 7, the additional devices are placed in a second bank to multiplex the signals. This reduces the number of wired-OR connections. Another solution is to put a small resistor in series with the output before the capacitive load to limit excessive ringing and oscillations. Figure 8 shows the graph of the Optimal Isolation Resistor vs. Capacitive Load. A lowpass filter is created from the series resistor and parasitic capacitance to ground. A single R-C do not affect the performance at video frequencies, but in a very large system there may be many R-Cs cascaded in series. The cumulative effect is a slight rolling off of the high frequencies causing a "softening" of the picture. There are two solutions to achieve higher performance. One way is to design the PC board traces associated with the outputs such that they exhibit some inductance. By routing the traces in a repeating "S" configuration, the traces that are nearest each other will exhibit a mutual inductance increasing the total inductance. This series inductance causes the amplitude response to increase or peak at higher frequencies, offsetting the rolloff from the parasitic capacitance. Another solution is to add a smallvalue inductor to the output.

#### *On-Screen Display Insertion*

The MAX4356 facilitates the insertion of on-screen graphics and characters by using the built-in fast 2:1 multiplexer associated with each of the 16 outputs (Functional Diagram). This mux switches in 40ns, much



*Figure 7. 64 x 16 Nonblocking Matrix with Reduced Capacitive Loading*

less than the width of a single pixel. Access to this fast mux is through 16 dedicated OSDFILL analog inputs and 16 dedicated OSDKEY input controls. OSD timing is externally controlled and applied to the OSDKEY inputs (Figure 1). Pulling OSDKEYi low switches the signal on the OSDFILL; input to the OUT; output. When the OSDKEY signal is logic high, the signal at IN\_ is switched to the output. This switching action is repeated on a pixel-by-pixel basis for each scan line. In this way any synchronized video signal, including arbitrary graphics, can be inserted on the screen (Figure 9).





*Figure 8. Optimal Isolation Resistor vs. Capacitive Load*

This technique for inserting OSD display information is an improvement over the way it has traditionally been done. Other OSD techniques require an external fast mux and a buffer for each output.

#### *Crosstalk Signal and Board Routing Issues*

Improper signal routing causes performance problems such as crosstalk. The MAX4356 has a typical crosstalk rejection of -62dB at 6MHz. A bad PC board layout degrades the crosstalk rejection by 20dB or more. To achieve the best crosstalk performance:

- 1) **Place ground isolation between long critical signal PC board trace runs.** These traces act as a shield to potential interfering signals. Crosstalk can be degraded by parallel traces as well as directly above and below on adjoining PC board layers.
- 2) **Maintain controlled-impedance traces.** Design as many of the PC board traces as possible to be  $75\Omega$ transmission lines. This lowers the impedance of the traces, reducing a potential source of crosstalk. More power will be dissipated due to the output buffer driving a lower impedance.

#### 3) **Minimize ground-current interaction by using a good ground plane strategy.**

In addition to crosstalk, another key issue of concern is isolation. Isolation is the rejection of undesirable feedthrough from input to output with the output disabled. The MAX4356 acheives a -110dB isolation at 6MHz by selecting the pinout configuration such that the inputs and outputs are on opposite sides of the package. Coupling through the power supply is a function of the quality and location of the supply bypassing. Use





*Figure 9. Improved Implementation of On-Screen Display*

appropriate low-impedance components and locate them as close as possible to the IC. Avoid routing the inputs near the outputs.

#### *Power-Supply Bypassing*

The MAX4356 operates from a single  $+5V$  or dual  $\pm 3V$ to  $\pm 5V$  supplies. For single-supply operation, connect all VEE pins to ground and bypass all power-supply pins with a 0.1µF capacitor to ground. For dual-supply systems, bypass all supply pins to ground with 0.1µF capacitors.

#### *Power in Large Systems*

The MAX4356 has been designed to operate with split supplies down to  $\pm 3V$  or a single supply of  $+5V$ . Operating at the minimum supply voltages reduces the power dissipation by as much 40% to 50%. At  $\pm$ 5V, the MAX4356 consumes 195mW (0.76mW/point).

#### *Driving a PC Board Interconnect or a Cable (AV = +1V/V or +2V/V)*

The MAX4356 output buffers can be programmed to either  $Ay = +1$ V/V or  $+2$ V/V. The  $+1$ V/V configuration is typically used when driving a short-length (less than 3cm), high-impedance "local" PC board trace. To drive a cable or a 75 $\Omega$  transmission line trace program the gain of the output buffer to +2V/V and place a  $75\Omega$ resistor in series with the output. The series termination resistor and the 75 $Ω$  load impedance act as a voltagedivider that divides the video signal in half. Set the gain to +2V/V to transmit a standard 1V video signal down a

cable. The series  $75\Omega$  resistor is called the back-match, reverse termination, or series termination. This  $75\Omega$ resistor reduces reflections, and provides isolation, increasing the output capacitive driving capability.

#### *Matrix Programming*

The MAX4356's unique digital interface simplifies programming multiple MAX4356 devices in an array. Multiple devices are connected with DOUT of the first device connecting to DIN of the second device, and so on (Figure 10). Two distinct programming modes, individual output address mode (MODE  $= 0$ ) and complete matrix mode (MODE = 1), are selected by toggling a single MODE control pin high or low. Both modes operate with the same physical board layout. This allows initial programming of the IC by daisy-chaining and sending one long data word while still being able to address immediately and update individual locations in the matrix.

#### **Individual Output Address Mode (Mode 0)**

In Individual Output Address Mode, the devices are connected in a serial bus configuration, with the data routing gate (Figure 3) connecting DIN to DOUT, making each device a virtual node on the serial bus. A single 16-bit control word is sent to all devices simultaneously. Only the device with the corresponding chip address responds to the programming word, and updates its output. In this mode, the chip address is set through hardware pin strapping of A3–A0. The host then communicates with the device by sending a 16-bit word consisting of 2 don't care MSB bits, 4 chip address bits, and 10 bits of data to make the word exactly 2 bytes in length. The 10 data bits are broken down into 4 bits to select the output to be programmed; 1 bit to set the output enable, 1 bit to set gain, and 4 bits to select the input to be connected to that output. In this method, the matrix is programmed one output at a time.

#### **Complete Matrix Mode (Mode 1)**

In Complete Matrix Mode, the devices are connected in a daisy-chain fashion where n x 96 bits are sent to program the entire matrix, and where  $n =$  the number of MAX4356 devices connected in series. This long data word is structured such that the first bit is the LSB of the last device in the chain and the last data bit is the MSB of the first device in the chain. The total length of the data word is equal to the number of crosspoint devices to be programmed in series, times 96 bits per crosspoint device. This programming method is most often used at startup to initially configure the switching matrix.

#### *+5V Single-Supply Operation with AV = +1V/V and +2V/V*

The MAX4356 quarantees operation with single  $+5V$ supply and gain of +1V/V for standard video input signals (1Vp-p). To implement a complete video matrix switching system capable of gain  $= +2V/V$  while operating with +5V single supply, combine the MAX4356 crosspoint switch with Maxim's low-cost, high-performance video amplifiers optimized for single +5V supply operation (Figure 11). The MAX4450 single and MAX4451 dual op amps are unity-gain-stable devices that combine high-speed performance with Rail-to-Rail<sup>®</sup> outputs. The common-mode input voltage range extends beyond the negative power-supply rail (ground in single-supply applications). The MAX4450 is available in the ultra-small 5-pin SC70 package, while the MAX4451 is available in a space-saving 8-pin SOT23. The MAX4383 is a quad op amp available in a 14-pin TSSOP package. The MAX4380/MAX4381/MAX4382 and MAX4384 offer individual output high-impedance disable making these amplifiers suitable for wired-OR connections.

*Rail-to-Rail is a registered trademark of Nippon Motorola, Ltd.*





*Figure 10. Matrix Mode Programming*



*Figure 11. Typical Single +5V Supply Application*

## *Chip Information*

TRANSISTOR COUNT: 24,883 PROCESS: BiCMOS

*MAX4356*

**MAX4356** 



#### *Package Information*



*Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.*

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